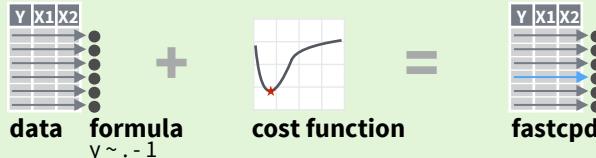


Change point analysis with fastcpd :: CHEATSHEET



Basics

fastcpd is based on the **Sequential Gradient Descent** and **Penalized Exact Linear Time**, avoiding repeated likelihood calculation and pruning impossible change points given a **data** set, a **cost** function, and optional **gradient / Hessian**.



Various built-in families are provided to better utilize the improved performance. A model of as simple as **data + family** is enough.



Complete the template below to find change points.

```
fastcpd(data = <DATA>,
        [family = "<FAMILY>" OR cost = <COST_FUNCTION>], required
        formula = <FORMULA>, beta = <NUMERIC>,
        segment_count = <INTEGER>, p = <INTEGER>,
        trim = <NUMERIC>, k = <FUNCTION(x)>,
        cost_gradient = <FUNCTION(data, theta)>,
        cost_hessian = <FUNCTION(data, theta)>, ...)
```

Not required, sensible defaults supplied

fastcpd(data = data, ...) Returns a "fastcpd" object containing the information used to call the method.

plot(fastcpd_result) Invokes `ggplot2` to plot the data.

summary(fastcpd_result) Outputs summary information of the call, including change point locations, estimated parameters and residuals for each segments.

family

Built-in families ready to use.

Regression and **time series** (case sensitive)

Regression - "gaussian", "binomial", "poisson", "lasso"

Time series - "ar", "var"

fastcpd

Use **fastcpd** to deal with all data types including the built-in families and any custom models, and **fastcpd_ts** to deal with **ar(p)** and **var(p)** time series.

LINEAR REGRESSION

```
result <- fastcpd(y ~ x.1 + x.2 - 1,
                    data = data.frame(y = y, x = x), family = "gaussian", ...)

... = segment_count = 10, trim = 0.05
... = beta = (p + 1) * log(nrow(data)) / 2 * variance
... = momentum_coef = 0.1, cp_only = TRUE
... = k = function(x) {
    if (x < n / 4) 2
    else if (x < n / 2) 1
    else 0
}
... = vanilla_percentage = 0, p = ncol(data) - 1
... = all possible combinations from above
epsilon: ignored min_prob: ignored
winsorise_minval/winsorise_maxval: ignored
cost/cost_gradient/cost_hessian: incompatible
```

LOGISTIC REGRESSION

```
result <- fastcpd(y ~ . - 1,
                    data = data.frame(y = y, x = x), family = "binomial", ...)

... = segment_count = 8, cp_only = FALSE
... = beta = (p + 1) * log(nrow(data)) / 2
... = momentum_coef = 0, trim = 0.03
... = k = function(x) {
    if (x < n / 4) 1
    else 0
}
... = vanilla_percentage = 0.1, epsilon = 1e-10
... = p = ncol(data) - 1
... = all possible combinations from above
min_prob: ignored
winsorise_minval/winsorise_maxval: ignored
cost/cost_gradient/cost_hessian: incompatible
```

POISSON REGRESSION

```
result <- fastcpd(y ~ . - 1,
                    data = data.frame(y = y, x = x), family = "poisson", ...)

... = segment_count = 6, cp_only = TRUE
... = beta = (p + 1) * log(nrow(data)) / 2
... = momentum_coef = 0.02, trim = 0.03
... = k = function(x) {
    if (x < n / 4) 1
    else 0
}
... = vanilla_percentage = 0.15, epsilon = 1e-5
... = p = ncol(data) - 1, min_prob = 10^10
... = winsorise_minval = -20
... = winsorise_maxval = 20
... = all possible combinations from above
cost/cost_gradient/cost_hessian: incompatible
```

PENALIZED LINEAR REGRESSION

```
result <- fastcpd(y ~ . - 1,
                    data = data.frame(y = y, x = x), family = "lasso", ...)

... = segment_count = 10, trim = 0.025
... = beta = (p + 1) * log(nrow(data)) / 2
... = momentum_coef = 0, cp_only = TRUE
... = k = function(x) {
    if (x < n / 4) 1
    else 0
}
... = vanilla_percentage = 0, p = ncol(data) - 1
... = all possible combinations from above
epsilon: ignored min_prob: ignored
winsorise_minval/winsorise_maxval: ignored
cost/cost_gradient/cost_hessian: incompatible
```

AR(p)

```
result <- fastcpd.ts(x, "ar", 3, ...)
result <- fastcpd(~ x - 1, data.frame(x), family = "ar", p = 3, ...)

... = segment_count = 8, cp_only = FALSE
... = beta = (p + 1) * log(nrow(data)) / 2 * variance
... = momentum_coef = 0, trim = 0.03
... = k = function(x) {
    if (x < n / 4) 1
    else 0
}
... = vanilla_percentage = 0.1
... = all possible combinations from above
epsilon: ignored min_prob: ignored
winsorise_minval/winsorise_maxval: ignored
cost/cost_gradient/cost_hessian: incompatible
```

VAR(p)

```
result <- fastcpd_ts(x, "var", 3, ...)
result <- fastcpd(~ . - 1, data.frame(x), family = "var", p = 3, ...)

... = segment_count = 6, cp_only = TRUE
... = beta = (p + 1) * log(nrow(data)) / 2
... = momentum_coef = 0.02, trim = 0.03
... = k = function(x) {
    if (x < n / 4) 1
    else 0
}
... = vanilla_percentage = 0.15
... = all possible combinations from above
epsilon: ignored min_prob: ignored
winsorise_minval/winsorise_maxval: ignored
cost/cost_gradient/cost_hessian: incompatible
```

UTILITY FUNCTION: PRINT

r\$> print(result_binomial)

Change points:
[1] 126

r\$> print(result_no_cp)

No change points found

r\$> print(result_custom)

Change points:
[1] 300 700

UTILITY FUNCTION: SUMMARY

r\$> summary(result_gaussian)

Call:
fastcpd(y ~ . - 1, data = data, family = "gaussian")

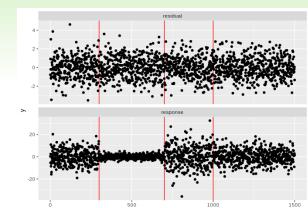
Change points:
98 202

Cost values:
53.44023 53.1441 45.04974

Parameters:
segment 1 segment 2 segment 3
1 0.9704022 -1.07884004 0.5925092
2 1.1786074 -0.01757927 -0.5287126

UTILITY FUNCTION: PLOT

r\$> plot(result_lasso)



r\$> plot(result_ar1)

