

# Implementing Reed-Solomon

Andrew Brown

# Recall

- Reed-Solomon represents messages as polynomials and over-samples them for redundancy.
- An  $(n, k, n - k + 1)$  code has
  - $k$  digit messages
  - $n$  digit codewords
  - $n - k + 1$  distance between codewords (at least)
  - $(n - k)/2$  errors before it cannot be decoded
  - $2s = n - k$
- In this presentation, all messages and codewords are over the finite field  $GF(2^8)$ . This makes byte-oriented implementation easy

# Recall

- Generator Polynomial:

- $g(x) = (x - \alpha)(x - \alpha^2) \cdots (x - \alpha^{n-k})$

- $\alpha$  is a generator element in  $GF(2^8)$

- Encoding Process:

- $m$  is the message encoded as a polynomial

- $m' = mx^{2s}$

- $b = m' \pmod{g}$

- $m' = qg + b$  for some  $q$

- $c = m' - b$

- Codewords are multiples of  $g$ , and are systematic

- Verifying a codeword is valid is a matter of checking for divisibility by  $g$

# Decoding Procedure Overview

1. **Calculate Syndromes**
2. **Berlekamp-Massey Algorithm** - calculates the Error Locator Polynomials and Error Evaluator Polynomials
3. **Chien Search** - Finds the error locations using the Error Locator Polynomial
4. **Forney's Formula** - Finds the error magnitudes using the error evaluator polynomial
5. **Correct the Errors**

# Decoding (Defining Terms)

## ● Error Polynomial

$$R(x) = C(x) + E(x)$$

$$E(x) = E_0 + E_1x + \cdots + E_{n-1}x^{n-1}$$

- Has at most  $s$  coefficients that are non-zero

## ● Error Positions

- $j_1, j_2, \cdots, j_s$ , each a value between 0 and  $n - 1$

## ● Error Locations

$$X_i = \alpha^{j_i}$$

## ● Error Magnitudes

$$Y_i = E_{j_i}$$

- Notice that there are  $2s$  unknowns

# Decoding (Syndromes)

- Step 1: Calculate the first  $2s$  syndromes
- Syndromes are defined for all  $l$ :

$$s_l = \sum_{i=1}^s Y_i X_i^l$$

- For the first  $2s$ , it reduces to:

$$s_l = E(\alpha^l) = \sum_{i=1}^s Y_i \alpha^{lj_i} \quad 1 \leq l \leq 2s$$

- $s_l = R(\alpha^l) = E(\alpha^l)$  for the first  $2s$  powers of  $\alpha$ .
- Equivalent to having  $2s$  equations with  $2s$  unknowns

# Decoding (Syndromes)

- Encode the syndromes in a generator polynomial:

$$s(z) = \sum_{i=1}^{\infty} s_i z^i$$

- This can be computed by finding each  $s_i$  from the received codeword for the first  $2s$  values. That's all we need though.

# Berlekamp-Massey Algorithm

- Input: Syndrome polynomial from the last slide
- Output: Error Locator Polynomial  $\sigma(z)$  and Error Evaluator Polynomial  $\omega(z)$ . Defined as:

$$\sigma(z) = \prod_{i=1}^s (1 - X_i z)$$

$$\omega(z) = \sigma(z) + \sum_{i=1}^s z X_i Y_i \prod_{\substack{j=1 \\ j \neq i}}^s (1 - X_j z)$$

- Notice that the error locations are the inverse roots of  $\sigma(z)$ . (Roots are  $1/X_1, 1/X_2, \dots, 1/X_s$ )



# B-M (The Key Equation)

- Observe the following relation:

$$\begin{aligned}\frac{\omega(z)}{\sigma(z)} &= 1 + \sum_{i=1}^s \frac{zX_iY_i}{1 - X_iz} \\ &= \dots \text{intermediate steps omitted} \\ &= 1 + s(z)\end{aligned}$$

- Key equation thus states:

$$(1 + s(z))\sigma(z) \stackrel{(\text{mod } z^{2s+1})}{=} \omega(z)$$

- $\sigma(z)$  and  $\omega(z)$  have degree at most  $s$
- Key Equation represents a set of  $2s$  equations and  $2s$  unknowns

# B-M (procedure)

- B-M iterates  $2s$  times
- At each iteration, it produces a pair of polynomials:

$$(\sigma_{(l)}(z), \omega_{(l)}(z))$$

- where the polynomials satisfy that iteration's key equation:

$$(1 + s(z))\sigma_{(l)}(z) \stackrel{(\text{mod } z^{l+1})}{=} \omega_{(l)}(z)$$

# B-M (procedure)

- Once we have

$$(\sigma_{(l)}(z), \omega_{(l)}(z))$$

for some  $l$ . If we're lucky, they already satisfy the next key equation:

$$(1 + s(z))\sigma_{(l)}(z) \stackrel{(\text{mod } z^{(l+2)})}{=} \omega_{(l)}(z)$$

in which case we can set  $\sigma_{(l+1)}(z) = \sigma_{(l)}(z)$  and similarly for  $\omega(z)$

- However, usually we have an unwanted higher-order term:

$$(1 + s(z))\sigma_{(l)}(z) \stackrel{(\text{mod } z^{l+2})}{=} \omega_{(l)}(z) + \Delta_{(l)}z^{l+1}$$

# B-M (procedure)

- $\Delta_{(l)}$  is the non-zero coefficient of  $z^{l+1}$  in  $(1 + s(z))\sigma_{(l)}(z)$
- Basic idea is to iteratively improve estimates of  $\sigma$  and  $\omega$
- But since there may be a higher order term, we can't always just extend to  $l + 1$  from iteration  $l$
- A complex set of rules determines how to handle different cases
- The next 5 slides describe these cases and how to handle them

# B-M (Details)

- $\Delta_{(l)}$  is the non-zero coefficient in  $(1 + s(z))\sigma_{(l)}(z)$
- To find the next iteration's polynomials, we introduce two more polynomials  $\tau_{(l)}(z)$  and  $\gamma_{(l)}(z)$
- They must satisfy:

$$(1 + s(z))\tau_{(l)}(z) \stackrel{(\text{mod } z^{l+1})}{=} \gamma_{(l)}(z) + z^l$$

- And we have the following rules to derive the next  $\sigma$  and  $\omega$ :

$$\sigma_{(l+1)}(z) = \sigma_{(l)}(z) - \Delta_{(l)}z\tau_{(l)}(z)$$

$$\omega_{(l+1)}(z) = \omega_{(l)}(z) - \Delta_{(l)}z\gamma_{(l)}(z)$$

# B-M (Details)

- But how to compute  $\tau_{(l+1)}(z)$  and  $\gamma_{(l+1)}(z)$ ?
- Use one of the following rules:

(A)	$\tau_{(l+1)}(z) =$	$z\tau_{(l)}(z)$
	$\gamma_{(l+1)}(z) =$	$z\gamma_{(l)}(z)$
(B)	$\tau_{(l+1)}(z) =$	$\frac{\sigma_{(l)}(z)}{\Delta_{(l)}}$
	$\gamma_{(l+1)}(z) =$	$\frac{\omega_{(l)}(z)}{\Delta_{(l)}}$

# B-M (Details)

- One of (A) or (B) is chosen each iteration to minimize the degrees of  $\tau_{(l+1)}(z)$  and  $\gamma_{(l+1)}(z)$
- To choose, define a single value  $D_{(l)}$  for each iteration
- Choose rule (A) if  $\Delta_{(l)} = 0$  or  $D_{(l)} > \frac{l+1}{2}$
- Choose rule (B) if  $\Delta_{(l)} \neq 0$  and  $D_{(l)} < \frac{l+1}{2}$
- With rule (A) set  $D_{(l+1)} = D_{(l)}$
- With rule (B) set  $D_{(l+1)} = l + 1 - D_{(l)}$
- These rules and conditions ensure  $0 < D_{(l+1)} \leq l + 1$  and the degrees of  $\sigma_{(l+1)}$  and  $\omega_{(l+1)}$  are upper-bounded by  $D_{(l+1)}$  and degrees of  $\tau_{(l+1)}$  and  $\gamma_{(l+1)}$  are upper-bounded by  $l - D_{(l)}$

# B-M (Details)

- But what about when  $\Delta_{(l)} \neq 0$  and  $D_{(l)} = \frac{l+1}{2}$ ?
- Either rule works, but to do even better, define one last value, a binary value  $B_{(l)}$ , for each iteration
- When  $B_{(l)} = 0$  use rule (A)
- When  $B_{(l)} = 1$  use rule (B)
- With rule (A) set  $B_{(l+1)} = B_{(l)}$
- With rule (B) set  $B_{(l+1)} = 1 - B_{(l)}$
- This keeps the degree inequalities satisfied:

$$\text{degree } \omega_{(l)}(z) \leq D_{(l)} - B_{(l)}$$

$$\text{degree } \gamma_{(l)}(z) \leq l - D_{(l)} - (1 - B_{(l)})$$



# B-M (Details)

- All those rules ensure the degrees of  $\sigma$  and  $\omega$  do not grow too large. Each step they satisfy:

$$\text{degree } \sigma_{(l)} \leq (l + 1)/2$$

$$\text{degree } \omega_{(l)} \leq l/2$$

- Last piece: the initial conditions:

$$\sigma_{(0)}(z) = 1$$

$$\omega_{(0)}(z) = 1$$

$$\tau_{(0)}(z) = 1$$

$$\gamma_{(0)}(z) = 0$$

$$D_{(0)} = 0$$

$$B_{(0)} = 0$$

# Decoding: Next Steps

- Now we have the Error Locator Polynomial  $\sigma(z)$  and the Error Evaluator Polynomial  $\omega(z)$
- Chien's Search takes  $\sigma(z)$  and outputs the error locations/positions ( $X_i$  and  $j_i$ )
- Forney's Formula takes  $\omega(z)$  and the array  $X_i$  of error locations outputs the error magnitudes ( $Y_i$ )

# Chien's Procedure

- Recall the definition of  $\sigma(z)$ :

$$\sigma(z) = \prod_{i=1}^s (1 - X_i z)$$

- Now that we have  $\sigma(z)$ , finding the array of  $X_i$  values is simply a matter of solving for the roots
- The Easy Way: since we're working over a small field, just test every value
  - Let  $\alpha$  be a generator
  - Initialize  $\{X_i\}$  to the empty set
  - For  $l = 1, 2, \dots$   
If  $\sigma(\alpha^l) = 0$ : add  $\alpha^{-l}$  to  $\{X_i\}$

# Chien's Procedure

- But we can do better than evaluating it 255 times!
- If we have computed the  $\alpha^l$ th evaluation, we get:

$$\sigma(\alpha^l) = 1 + \sigma_1\alpha^l + \sigma_2\alpha^{2l} + \sigma_3\alpha^{3l} + \cdots + \sigma_s\alpha^{sl}$$

- Then, computing  $\sigma(\alpha^{l+1})$  is an  $O(s)$  operation:

$$\sigma(\alpha^{l+1}) = 1 + \sigma_1\alpha^{l+1} + \sigma_2\alpha^{2l+2} + \sigma_3\alpha^{3l+3} + \cdots + \sigma_s\alpha^{sl+s}$$

- The  $i$ th term in  $\sigma(\alpha^{l+1})$  can be computed from the  $i$ th term in  $\sigma(\alpha^l)$  by multiplying that term by  $\alpha^i$

# Forney's Formula

Using the Error Evaluator Polynomial  $\omega(z)$  and the error locations  $\{X_i\}$ , the error magnitudes  $\{Y_i\}$  can be computed

$$\omega(z) = \sigma(z) + \sum_{i=1}^s z X_i Y_i \prod_{\substack{j=1 \\ j \neq i}}^s (1 - X_j z)$$

Evaluate at  $X_l^{-1}$

$$\omega(X_l^{-1}) = \sigma(X_l^{-1}) + \sum_{i=1}^s X_l^{-1} X_i Y_i \prod_{\substack{j=1 \\ j \neq i}}^s (1 - X_j X_l^{-1})$$

# Forney's Formula

$$\omega(X_l^{-1}) = \sigma(X_l^{-1}) + \sum_{i=1}^s X_l^{-1} X_i Y_i \prod_{\substack{j=1 \\ j \neq i}}^s (1 - X_j X_l^{-1})$$

Then simplifies to:

$$= Y_l \prod_{\substack{j=1 \\ j \neq l}}^s (1 - X_j X_l^{-1})$$

since  $\sigma(X_l^{-1}) = 0$

# Forney's Formula

$$\omega(X_l^{-1}) = Y_l \prod_{\substack{j=1 \\ j \neq l}}^s (1 - X_j X_l^{-1})$$

Can then be solved for  $Y_l$ :

$$Y_l = \frac{\omega(X_l^{-1})}{\prod_{\substack{j=1 \\ j \neq l}}^s (1 - X_j X_l^{-1})}$$

And that can be directly computed. We know all the values on the right hand side!

# Putting it all together

- We know:
  - $\{X_i\}$  The error locations
  - $\{Y_i\}$  The error magnitudes
- Put them together to build the Error Polynomial  $E(x)$
- Then subtract to get the codeword!

$$C(x) = R(x) - E(x)$$



# Reed-Solomon Implementation

The rest of the presentation is about my implementation

- Done in Python with no external libraries or dependencies
- Implemented a Finite Field class for  $GF(2^8)$
- Implemented a Polynomial Class for manipulating polynomials
- Implemented the RS algorithms as described

# Finite Fields

- Created a Python class that subclasses `int`
- Instances are integers, which represent the corresponding finite field element when translated to a polynomial

$$51 = 00110011 = x^5 + x^4 + x + 1$$

- Overwrote addition, subtraction, multiplication, division, and exponentiation for finite field arithmetic
- Multiplication defined using an exponentiation table and a logarithm table, pre-generated

# Finite Fields (multiplication)

```
exptable = (1, 3, 5, 15, 17, 51, ... 246, 1)
```

- This table holds all powers of 3

- `exptable[1] = 3`

- `exptable[255] = 1`

```
logtable = (None, 0, 25, 1, 50, 2, ... 112, 7)
```

- This table holds all logarithms in base 3

- `logtable[3] = 1`

- `logtable[17] = 4`  
(since  $3^4 = 17$ )

- `logtable[0]`  
is an error

# Finite Fields (multiplication)

```
exptable = (1, 3, 5, 15, 17, 51, ... 246, 1)
logtable = (None, 0, 25, 1, 50, 2, ... 112, 7)
```

● These tables together define multiplication like this:

```
def multiply(a, b):
    x = logtable[a]
    y = logtable[b]
    z = (x + y) % 255
    return exptable[z]
```

# Finite Fields (more)

```
exptable = (1, 3, 5, 15, 17, 51, ... 246, 1)
logtable = (None, 0, 25, 1, 50, 2, ... 112, 7)
```

- Exponentiation and multiplicative inverses also use these tables:

```
def power(a, b):
    x = logtable[a]
    z = (x * b) % 255
    return exptable[z]
```

```
def inverse(a):
    e = logtable[a]
    return exptable[255 - e]
```

# Polynomial Class

- Stores numbers from high degree to low degree
- All coefficient math is done using regular Python operators
- Compatible with both integers and field elements as coefficients
- Supports long division and remainders (essential for RS coding)

# Reed Solomon Encoding

Since the polynomial class abstracts polynomial math away, encoding boils down to basically:

```
def encode(m):  
    mprime = m * xshift  
    b = mprime % g  
    c = mprime - b  
    return c
```

# Reed Solomon Decoding

Decoding is also fairly simple:

```
def decode(r):  
    sz = syndromes(r)  
    sigma, omega = berlekamp_massey(sz)  
    X, j = chien_search(sigma)  
    Y = forney(omega, X)  
  
    # There is a loop to build E here  
    ...  
  
    return r - E
```



# Reed Solomon Decoding

- My implementation of those functions are straight up implementations of the math. Nothing surprising.

```
def syndromes(r):  
    s = [GF256int(0)]  
    for l in range(1, n-k+1):  
        s.append(r.evaluate(GF256int(3)**l))
```

- My Chien Search isn't actually Chien's search though, it just evaluates the polynomial 255 times:

```
p = GF256int(3)  
for l in range(1, 256):  
    if sigma.evaluate( p**l ) == 0:  
        X.append( p**(-l) )  
        j.append( 255 - l)
```

# Implementation Notes

- Message to Polynomial translations
  1. “hello”
  2. 104, 101, 108, 108, 111
  3.  $104x^4 + 101x^3 + 108x^2 + 108x^1 + 111$
- Messages are effectively left-padded with null bytes

# Example

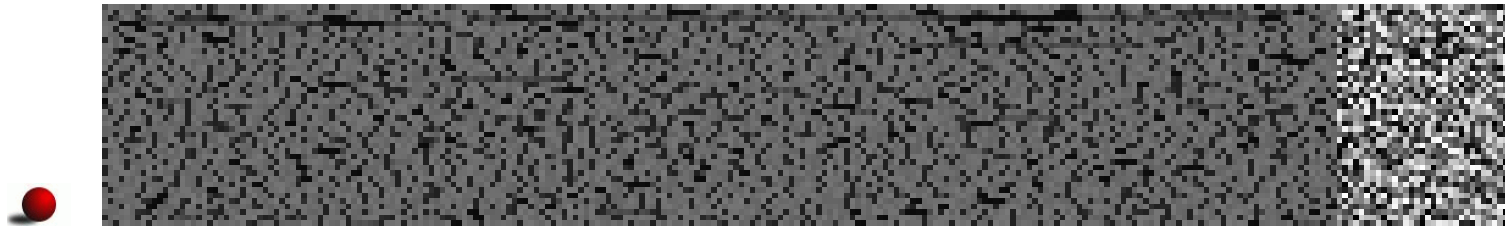
- RS(20,13) code: 13 message bytes and 7 parity bytes. Can correct 3 errors.
- Message: “Hello, world!”
- Codeword: “Hello, world![8d][13][f4][f9][43][10][e5]”
- R: “[00][00][00]lo, world![8d][13][f4][f9][43][10][e5]”
- Decoded: “Hello, world!”

And, to prove this isn't faked...

# Demo!

As an example, I have written a program that encodes codewords as rows in an image

- Uses RS(255,223)
- Encodes each symbol as a pixel in a grayscale image
- Each row is a codeword



- Decodes to:

ALICE'S ADVENTURES IN WONDERLAND

Alice was beginning to get very tired of  
sitting by her sister on the ...

# Demo!

- Since each row is a RS(255,223) codeword, it can handle up to 16 pixel errors per row.
- Drawing 5 px stripes, each of the following still decodes:

