

1 SBIAX: Density-estimation simulation-based inference 2 in JAX

3 **Jed Homer** ^{1,2*} and **Oliver Friedrich** ^{1,2,3*}

4 ¹ University Observatory, Faculty for Physics, Ludwig-Maximilians-Universität München, Scheinerstrasse
5 1, München, Deutschland. ² Munich Center for Machine Learning. ³ Excellence Cluster
6 ORIGINS, Boltzmannstr. 2, 85748 Garching, Deutschland. * These authors contributed equally.

DOI: [10.xxxxx/draft](https://doi.org/10.xxxxx/draft)

Software

- [Review](#) 
- [Repository](#) 
- [Archive](#) 

Editor: [Open Journals](#) 

Reviewers:

- [@openjournals](#)

Submitted: 01 January 1970

Published: unpublished

License

Authors of papers retain copyright
and release the work under a
Creative Commons Attribution 4.0
International License ([CC BY 4.0](#)).

In partnership with



AMERICAN
ASTRONOMICAL
SOCIETY

This article and software are linked
with research article DOI
[10.3847/xxxxx](https://doi.org/10.3847/xxxxx) <- [update this](#)
[with the DOI from AAS once you](#)
[know it.](#), published in the
Astrophysical Journal <- The
name of the AAS journal..

7 Summary

8 In a typical Bayesian inference problem, the data likelihood is not known. However, in recent
9 years, machine learning methods for density estimation can allow for inference using an estimator
10 of the data likelihood. This likelihood estimator is fit with neural networks that are trained on
11 simulations to maximise the likelihood of the simulation-parameter pairs - one of the many
12 available tools for Simulation Based Inference (SBI), ([Cranmer et al., 2020](#)). In such analyses,
13 density-estimation simulation-based inference methods can derive a posterior, which typically
14 involves

- simulating a set of data and model parameters $\{(\xi, \pi)_0, \dots, (\xi, \pi)_N\}$,
- obtaining a measurement $\hat{\xi}$,
- compressing the simulations and the measurements - usually with a neural network or linear compression - to a set of summaries $\{(x, \pi)_0, \dots, (x, \pi)_N\}$ and \hat{x} ,
- fitting an ensemble of normalising flow or similar density estimation algorithms (e.g. a Gaussian mixture model),
- the optional optimisation of the parameters for the architecture and fitting hyper-parameters of the algorithms,
 - – sampling the ensemble posterior (using an MCMC-sampler if the likelihood is fit directly), conditioned on the data-vector, to obtain parameter constraints on the parameters of a physical model, π .

26 sbiax is a software package that implements each of these steps. The code allows for
27 Neural Likelihood Estimation ([Alsing et al., 2019](#); [Papamakarios, 2019](#)), and Neural Posterior
28 Estimation ([Greenberg et al., 2019](#)).

29 As shown in Homer et al. ([2024](#)), SBI can successfully obtain the correct posterior widths and
30 coverages given enough simulations which agree with the analytic solution - this software was
31 used in the research for this publication.

32 Statement of need

33 Simulation Based Inference (SBI) covers a broad class of statistical techniques such as
34 Approximate Bayesian Computation (ABC) ([Rubin, 1984](#)), Neural Ratio Estimation (NRE)
35 ([Delaunoy et al., 2022](#)), Neural Likelihood Estimation (NLE), and Neural Posterior Estimation
36 (NPE). These techniques can derive posterior distributions, conditioned of noisy data vectors,
37 in a rigorous and efficient manner with assumptions on the data likelihood. In particular,
38 density-estimation methods have emerged as a promising method, given their efficiency, in
39 which generative models are used to fit likelihoods or posteriors directly using simulations.

40 In the field of cosmology, SBI is of particular interest due to complexity and non-linearity of

41 models for the expectations of non-standard summary statistics of the large-scale structure, as
42 well as the non-Gaussian noise distributions for these statistics. The assumptions required for
43 the complex analytic modelling of these statistics - as well as the increasing dimensionality of
44 data returned by spectroscopic and photometric galaxy surveys, limit the amount of information
45 that can be obtained on fundamental physical parameters. Therefore, the study and research
46 into current and future statistical methods for Bayesian inference is of paramount importance
47 for cosmology, especially in light of current and next-generation survey missions such as DES
48 (Laureijs et al., 2011), DESI (Levi et al., 2019), and Euclid (Laureijs et al., 2011).

49 The software we present, sbi_{ax}, is designed to be used by machine learning and physics
50 researchers for running Bayesian inferences using density-estimation SBI techniques. These
51 models can be fit easily with multi-accelerator training and inference within the code. This
52 software - written in jax (Bradbury et al., 2018) - allows for seamless integration of cutting
53 edge generative models to SBI, including continuous normalising flows (Grathwohl et al., 2018),
54 matched flows (Lipman et al., 2023), masked autoregressive flows (Papamakarios et al., 2018;
55 Ward, 2024), and Gaussian mixture models - all of which are implemented in the code. The
56 code features integration with the optuna (Akiba et al., 2019) hyper-parameter optimisation
57 framework which would be used to ensure consistent analyses, blackjax (Cabezas et al., 2024)
58 for fast MCMC sampling, and equinox (Kidger & Garcia, 2021) for neural network methods.
59 The design of sbi_{ax} allows for new density estimation algorithms to be trained and sampled
60 from, as long as they conform to a simple and typical design pattern demonstrated in sbi_{ax}.

61 Whilst excellent software packages already exist for conducting simulation-based inference
62 (e.g. sbi (Tejero-Cantero et al., 2020), sbijax (Dirmeir, 2024)) for some applications it is
63 useful to have a lightweight implementation that focuses on speed, ensembling of density
64 estimators and easily integrated MCMC sampling (e.g. for ensembles of likelihoods) - all of
65 which is based on a lightweight and regularly maintained jax machine learning library such
66 as equinox (Kidger & Garcia, 2021). sbi_{ax} depends on density estimators and compression
67 modules - as long as log-probability and callable methods exists for these, they can be integrated
68 seamlessly.

69 Density estimation with normalising flows

70 The use of density-estimation in SBI has been accelerated by the advent of normalising
71 flows. These models parameterise a change-of-variables $\mathbf{y} = f_\phi(\mathbf{x}; \boldsymbol{\pi})$ between a simple
72 base distribution (e.g. a multivariate unit Gaussian $\mathcal{G}[z|\mathbf{0}, \mathbf{I}]$) and an unknown distribution
73 $q(\mathbf{x}|\boldsymbol{\pi})$ (from which we have simulated samples \mathbf{x}). Naturally, this is of particular importance
74 for inference problems in which the likelihood is not known. The change-of-variables is fit
75 from data by training neural networks to model the transformation in order to maximise the
76 log-likelihood of the simulated data \mathbf{x} conditioned on the parameters $\boldsymbol{\pi}$ of a simulator model.
77 The mapping is expressed as

$$\mathbf{y} = f_\phi(\mathbf{x}; \boldsymbol{\pi}),$$

78 where ϕ are the parameters of the neural network. The log-likelihood of the flow is expressed
79 as

$$\log p_\phi(\mathbf{x}|\boldsymbol{\pi}) = \log \mathcal{G}[f_\phi(\mathbf{x}; \boldsymbol{\pi})|\mathbf{0}, \mathbf{I}] + \log |\mathbf{J}_{f_\phi}(\mathbf{x}; \boldsymbol{\pi})|,$$

80 This density estimator is fit to a set of N simulation-parameter pairs $\{(\boldsymbol{\xi}, \boldsymbol{\pi})_0, \dots, (\boldsymbol{\xi}, \boldsymbol{\pi})_N\}$ by
81 minimising a Monte-Carlo estimate of the KL-divergence

$$\begin{aligned}
 \langle D_{KL}(q||p_\phi) \rangle_{\pi \sim p(\pi)} &= \int d\pi p(\pi) \int dx q(x|\pi) \log \frac{q(x|\pi)}{p_\phi(x|\pi)}, \\
 &= \int d\pi \int dx p(\pi, x) [\log q(x|\pi) - \log p_\phi(x|\pi)], \\
 &\geq - \int d\pi \int dx p(\pi, x) \log p_\phi(x|\pi), \\
 &\approx -\frac{1}{N} \sum_{i=1}^N \log p_\phi(x_i|\pi_i), \tag{1}
 \end{aligned}$$

82 where $q(x|\pi)$ is the unknown likelihood from which the simulations x are drawn. This applies
 83 similarly for an estimator of the posterior (instead of the likelihood as shown here) and is the
 84 basis of being able to estimate the likelihood or posterior directly when an analytic form is
 85 not available. If the likelihood is fit from simulations, a prior is required and the posterior is
 86 sampled via an MCMC-sampler given some measurement. This is implemented within the
 87 code.

88 An ensemble of density estimators (with parameters - e.g. the weights and biases of the
 89 networks - denoted by $\{\phi_0, \dots, \phi_J\}$) has a likelihood which is written as

$$p_{\text{ensemble}}(\xi|\pi) = \sum_{j=1}^J \alpha_j p_{\phi_j}(\hat{\xi}|\pi)$$

90 where

$$\alpha_i = \frac{\exp(p_{\phi_i}(\hat{\xi}|\pi))}{\sum_{j=1}^J \exp(p_{\phi_j}(\hat{\xi}|\pi))}$$

91 are the weights of each density estimator in the ensemble. This ensemble likelihood can
 92 be easily sampled with an MCMC-sampler. In Figure 1 we show an example posterior from
 93 applying SBI, with our software, using two compression methods separately.

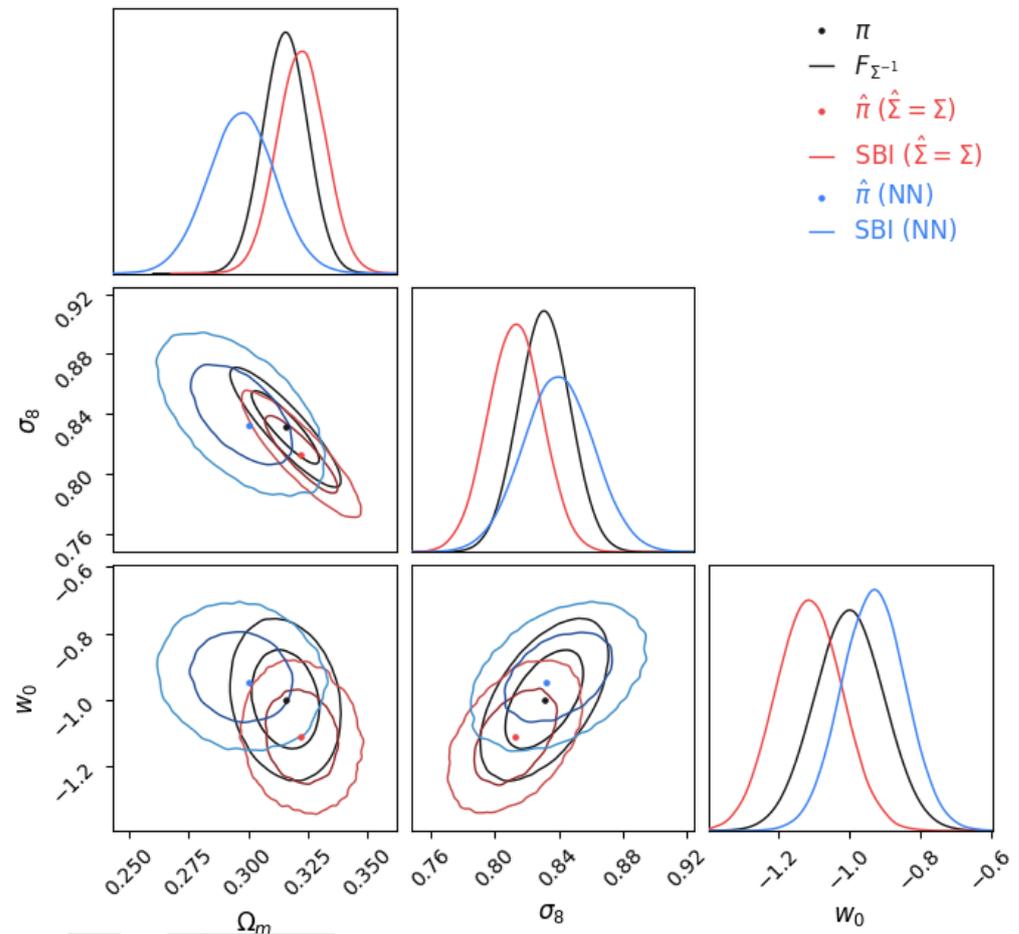


Figure 1: An example of posteriors derived with sbi-ax. We fit an ensemble of two continuous normalising flows to a set of simulations of cosmic shear two-point functions. The expectation $\xi[\pi]$ is linearised with respect to π and a theoretical data covariance model Σ (in this example) allows for easy sampling of many simulations - an ideal test arena for SBI methods. We derive two posteriors, from separate experiments, where a linear (red) or neural network compression (blue) is used. In black, the true analytic posterior is shown. Note that for a finite set of simulations the blue posterior will not overlap completely with the black and red posteriors - we explore this effect upon the posteriors from SBI methods, due to an unknown data covariance, in Homer et al. (2024).

Acknowledgements

94

95 We thank the developers of the packages jax (Bradbury et al., 2018), blackjax (Cabezas et
96 al., 2024), optax (DeepMind et al., 2020), equinox (Kidger & Garcia, 2021), diffrax (Kidger,
97 2022) and flowjax (Ward, 2024) for their work and for making their code available to the
98 community.

References

99

100 Akiba, T., Sano, S., Yanase, T., Ohta, T., & Koyama, M. (2019). Optuna: A next-generation
101 hyperparameter optimization framework. *The 25th ACM SIGKDD International Conference*
102 *on Knowledge Discovery & Data Mining*, 2623–2631.

- 103 Alsing, J., Charnock, T., Feeney, S., & Wandelt, B. (2019). Fast likelihood-free cosmology with
104 neural density estimators and active learning. *Monthly Notices of the Royal Astronomical*
105 *Society*. <https://doi.org/10.1093/mnras/stz1960>
- 106 Bradbury, J., Frostig, R., Hawkins, P., Johnson, M. J., Leary, C., Maclaurin, D., Necula, G.,
107 Paszke, A., VanderPlas, J., Wanderman-Milne, S., & Zhang, Q. (2018). *JAX: Composable*
108 *transformations of Python+NumPy programs* (Version 0.3.13). [http://github.com/jax-ml/](http://github.com/jax-ml/jax)
109 [jax](http://github.com/jax-ml/jax)
- 110 Cabezas, A., Corenflos, A., Lao, J., & Louf, R. (2024). *BlackJAX: Composable Bayesian*
111 *inference in JAX*. <https://arxiv.org/abs/2402.10797>
- 112 Cranmer, K., Brehmer, J., & Louppe, G. (2020). The frontier of simulation-based inference.
113 *Proceedings of the National Academy of Sciences*, 117(48), 30055–30062. [https://doi.](https://doi.org/10.1073/pnas.1912789117)
114 [org/10.1073/pnas.1912789117](https://doi.org/10.1073/pnas.1912789117)
- 115 DeepMind, Babuschkin, I., Baumli, K., Bell, A., Bhupatiraju, S., Bruce, J., Buchlovsky, P.,
116 Budden, D., Cai, T., Clark, A., Danihelka, I., Dedieu, A., Fantacci, C., Godwin, J., Jones,
117 C., Hemsley, R., Hennigan, T., Hessel, M., Hou, S., ... Viola, F. (2020). *The DeepMind*
118 *JAX Ecosystem*. <http://github.com/google-deepmind>
- 119 Delaunoy, A., Hermans, J., Rozet, F., Wehenkel, A., & Louppe, G. (2022). *Towards reliable*
120 *simulation-based inference with balanced neural ratio estimation*. [https://arxiv.org/abs/](https://arxiv.org/abs/2208.13624)
121 [2208.13624](https://arxiv.org/abs/2208.13624)
- 122 Dirmeir, S. (2024). *SBIJAX: Simulation-based inference in JAX*. (Version 0.3.0). [https:](https://github.com/dirmeir/sbijax)
123 [//github.com/dirmeir/sbijax](https://github.com/dirmeir/sbijax)
- 124 Grathwohl, W., Chen, R. T. Q., Bettencourt, J., Sutskever, I., & Duvenaud, D. (2018).
125 *FFJORD: Free-form continuous dynamics for scalable reversible generative models*. [https:](https://arxiv.org/abs/1810.01367)
126 [//arxiv.org/abs/1810.01367](https://arxiv.org/abs/1810.01367)
- 127 Greenberg, D. S., Nonnenmacher, M., & Macke, J. H. (2019). *Automatic posterior transfor-*
128 *mation for likelihood-free inference*. <https://arxiv.org/abs/1905.07488>
- 129 Homer, J., Friedrich, O., & Gruen, D. (2024). *Simulation-based inference has its own*
130 *Dodelson-Schneider effect (but it knows that it does)*. <https://arxiv.org/abs/2412.02311>
- 131 Kidger, P. (2022). *On neural differential equations*. <https://arxiv.org/abs/2202.02435>
- 132 Kidger, P., & Garcia, C. (2021). Equinox: Neural networks in JAX via callable PyTrees and
133 filtered transformations. *Differentiable Programming Workshop at Neural Information*
134 *Processing Systems 2021*.
- 135 Laureijs, R., Amiaux, J., Arduini, S., Auguères, J. -L., Brinchmann, J., Cole, R., Cropper, M.,
136 Dabin, C., Duvet, L., Ealet, A., Garilli, B., Gondoin, P., Guzzo, L., Hoar, J., Hoekstra, H.,
137 Holmes, R., Kitching, T., Maciaszek, T., Mellier, Y., ... Zucca, E. (2011). *Euclid definition*
138 *study report*. <https://arxiv.org/abs/1110.3193>
- 139 Levi, M. E., Allen, L. E., Raichoor, A., Baltay, C., BenZvi, S., Beutler, F., Bolton, A., Castander,
140 F. J., Chuang, C.-H., Cooper, A., Cuby, J.-G., Dey, A., Eisenstein, D., Fan, X., Flaugher,
141 B., Frenk, C., Gonzalez-Morales, A. X., Graur, O., Guy, J., ... Zu, Y. (2019). *The dark*
142 *energy spectroscopic instrument (DESI)*. <https://arxiv.org/abs/1907.10688>
- 143 Lipman, Y., Chen, R. T. Q., Ben-Hamu, H., Nickel, M., & Le, M. (2023). *Flow matching for*
144 *generative modeling*. <https://arxiv.org/abs/2210.02747>
- 145 Papamakarios, G. (2019). *Neural density estimation and likelihood-free inference*. [https:](https://arxiv.org/abs/1910.13233)
146 [//arxiv.org/abs/1910.13233](https://arxiv.org/abs/1910.13233)
- 147 Papamakarios, G., Pavlakou, T., & Murray, I. (2018). *Masked autoregressive flow for density*
148 *estimation*. <https://arxiv.org/abs/1705.07057>

- 149 Rubin, D. B. (1984). Bayesianly Justifiable and Relevant Frequency Calculations for the
150 Applied Statistician. *The Annals of Statistics*, 12(4), 1151–1172. [https://doi.org/10.1214/
151 aos/1176346785](https://doi.org/10.1214/aos/1176346785)
- 152 Tejero-Cantero, A., Boelts, J., Deistler, M., Lueckmann, J.-M., Durkan, C., Gonçalves, P. J.,
153 Greenberg, D. S., & Macke, J. H. (2020). Sbi: A toolkit for simulation-based inference.
154 *Journal of Open Source Software*, 5(52), 2505. <https://doi.org/10.21105/joss.02505>
- 155 Ward, D. (2024). *FlowJAX: Distributions and normalizing flows in JAX* (Version 16.0.0).
156 <https://doi.org/10.5281/zenodo.10402073>

DRAFT